

Supplemental material to 'Ensemble Learning for Confidence Measures in Stereo Vision'

Ralf Haeusler
Computer Science Department
The University of Auckland
r.haeusler@aucklanduni.ac.nz

Rahul Nair, and Daniel Kondermann
Heidelberg Collaboratory for Image Processing
University of Heidelberg
<http://hci.iwr.uni-heidelberg.de>

Abstract

In this supplemental material, we include sparsification plots for all 194 frames of the KITTI stereo dataset. For preserving clarity of plots we include only the following confidence features computed at full resolution in addition to results of bad pixel class posterior probabilities using random forests: Perturbation, Left-Right difference, disparity variance, peak ratio, semi global matching energy.

In contrast to previous evaluation with equal stereo result and confidence feature computation [1], in this study the evaluation domain differs slightly:

First, here we do not exclude locations which were found to be occluded based on Left-Right consistency check. This is due to us observing rather poor accuracy of the standard occlusion check [2] on recorded data. It would be of interest to run the same evaluation with ground truth based occlusions excluded. These are not part of published KITTI data.

Second, in this study we exclude a broader rim of 12 pixels (instead of 3) along image borders for evaluation, the reason being that each computed disparity result should be based on dataterm values. Due to adding scale-space features in this study, the adaptation is necessary.

Frames 43, 71, 82, 87, 94, 120, 122 and 180 are not representative for quality of random forest based results, as these frames are part of the training set.

- [2] H. Hirschmüller. Stereo processing by semiglobal matching and mutual information. *IEEE Trans. Pattern Anal. Mach. Intell.*, 30(2):328–341, 2008. 1

References

- [1] R. Haeusler and R. Klette. Analysis of KITTI Data for Stereo Analysis with Stereo Confidence Measures. In A. Fusiello, V. Murino, and R. Cucchiara, editors, *ECCV Workshops (2)*, volume 7584 of *Lecture Notes in Computer Science*, pages 158–167. Springer, 2012. 1







