Dynamic Attention Aggregation with BERT for Neural Machine Translation

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Abstract—The recently proposed BERT has demonstrated great power in various natural language processing tasks. However, the model does not perform effectively on cross-lingual tasks, especially on machine translation. In this work, we propose three methods to introduce pre-trained BERT into neural machine translation without fine-tuning. Our approach consists of a) a linear-attention aggregation that leverages a parameter matrix to capture the key knowledge of BERT, b) a self-attention aggregation which aims to learn what is vital for input and output, and c) a switch-gate aggregation to dynamically control the balance of the information flowing from the pre-trained BERT or the NMT model. We conduct experiments on several translation benchmarks and substantially improve over 2 BELU points on the IWSLT'14 English - German task with switch-gate aggregation method compared to a strong baseline, while our proposed model also performs remarkably on the other tasks.

I. INTRODUCTION

Pre-training Language Models (LM) like ELMO [1], BERT [2], GPT-2 [3], [4], cross-lingual language model (XLM) [5] and MASS [6] have significantly boost the performances of several natural language processing (NLP) tasks by transferring prior knowledge learned from large amount of unlabeled data to downstream tasks [1], such as classification, question answering, and sequence labeling. Among these different pretraining mechanisms, BERT [2], which employs Transformer encoder architecture [7] and trains a bi-directional LM, has become one of the most successful techniques. Since then, there are large numbers of variants of BERT, like XLNet [8], RoBERTa [9], which achieve state-of-the-art benchmarks [10] for many NLP tasks.

In recent years, Neural Machine Translation (NMT) has achieved remarkable performance on large-scale parallel corpora [11], [12], [13]. Considering the complexity of existing NMT models, it is difficult to improve the effectiveness directly. Naturally, the idea of using pre-trained models to improve the performance of machine translation has arisen and is brought up by some researchers [5], [6], [14]. However, due to the limitation of computing resources, training a pre-trained model from scratch is difficult [15]. Thus, we consider using the existing pre-trained BERT model to improve the effectiveness of machine translation.

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However, incorporating BERT into NMT is quite challenging and using BERT directly doesn't always achieve satisfactory results. Compared with other tasks where direct BERT fine-tuning works well, NMT has two distinct features, the availability of large amounts of training corpora and the high capacity of the baseline NMT models (i.e. Transformer) [16], which need lots of updating steps to adapt to the high-capacity model well on large-scale data [17]. However, updating overmuch causes BERT to forget universal knowledge from pre-training, which is named the *catastrophic forgetting problem* [18].

The existing practical accomplishments are integrating BERT as an additional representation into each layer of the encoder or decoder [15], or using BERT as a teacher model to guide the training on Transformer encoder side [17]. However, in BERT-fused NMT [15], the fusion method of pre-trained BERT and Transformer encoder or decoder layer representation is relatively simple (just averaged). Moreover, the settings of the drop-net trick during the training and inference are not consistent, and the authors have not explained this. In CTNMT [17], there is no improvement on the decoder side.

In this work, we propose three new fusion methods of pretrained BERT and Transformer encoder or decoder layer representation, which follow the previous work (BERT-fused NMT; CTNMT). Firstly, at each layer of the encoder and decoder, we introduce a parameter matrix to weigh the representations of BERT and vanilla NMT. The vanilla NMT model represents in-domain information of the input, while the BERT model represents out-of-domain information of the input. Intuitively, the importance of the two parts can be automatically measured by a parameter matrix. secondly, we use a self-attention mechanism to incorporate BERT into vanilla NMT, which can learn the word dependencies within a sentence and capture the internal structure of the sentence. Thirdly, We utilize a switch gate mechanism, inspired by the significant results on gated recurrent units in RNN [19]. Different from CTNMT, we add switch gates at each layer of the encoder and decoder. As each layer of Transformer will learn different features of the input (for example, shallow layers learn syntactic information and deep ones learn semantic information) [20], [21], integrating BERT with each level of the Transformer can better introduce the knowledge of BERT to the input adequately. Similarly,

each layer of BERT also represents different syntactic and semantic information [22], [23]. In this study, we compare the fusion results of different BERT and Transformer layers.

We conduct experiments on WMT and IWSLT tasks. For IWSLT tasks, our experiments on English \rightarrow German, German \rightarrow English and English \rightarrow French datasets show gains of up to 2.13, 1.22 and 1.16 BLEU scores respectively. For WMT tasks, with Transformer-base architecture, we increase 2.14 BELU scores compared to a strong baseline on En \rightarrow De dataset, and even surpass some models whose parameters are far more than our model. Experimental results demonstrate that our model can significantly outperform the strong standard baseline (i.e. Transformer).

The main contributions of our works can be summarized as:

- We propose three new attention aggregation methods to dynamically incorporate BERT into Neural Machine Translation with a Transformer-based framework.
- We empirically show that fusion different layers of BERT and vanilla NMT model have an important impact on the translation effect.
- Our approaches achieve significant improvements over the strong baseline Transformer model on three common translation datasets.

The rest parts of this paper are as follows. Related work is introduced in Section 2. The Approach of our model is reported in Section 3. Then we show our experiment details in Section 4. Finally, in Section 5, we conclude our work and further discuss some future plans.

II. RELATED WORK

With the latest advances and performance improvements in neural networks, pre-training technology develops rapidly. After Mikolov et al. [24] and Pennington et al. [25] proposing word2vec and Glove, we could apply distributional representations to individual words, which greatly improved the capability of NLP models. ELMO [1] proposed to merge the different network layers to obtain effective word representations, based on the bi-directional LSTM model [26], which was widely applied to question answering, textual entailment, etc. Inspired by ELMO, Radford et al. [3] employed a selfattention network based language model (GPT) to replace the BI-LSTM structure, which further improved the performance of the pre-training model. Then, BERT [2] appeared, which was one of the widely adopted pre-training approaches for model initialization. The structure of BERT is evolved from the encoder of Transformer [7]. Owing to the great achievements of BERT on various NLP tasks, variants of BERT have been proposed. Lample et al. [5] adapted the objectives of BERT to incorporate cross-lingual supervision from parallel data to learn cross-lingual language models (XLM). Masked Sequence to Sequence Pre-training (MASS) [6] adopted the encoderdecoder framework to reconstruct a sentence fragment from the remaining part of the sentence that had not been masked [27].

Several approaches had been proposed recently to incorporate BERT into Neural Machine Translation. Intuitively, the

conventional method was using the BERT model to initialize the NMT model and then fine-tuning it on downstream tasks, but it was even worse than the standard Transformer without using BERT [15]. Another common approach of utilizing BERT was employing it as inputs to the NMT model [1]. Although it was better than the fine-tuning ones, it did not make the most use of BERT in NMT, and also had not improved significantly.

Based on the above two traditional methods, [15] proposed a new algorithm, BERT-fused NMT, in which they fed BERT into all Transformer encoder and decoder layers by introducing attention mechanism rather than just using BERT as input embeddings only. Almost at the same time, [17] put forward CTNMT, a model that contained three techniques to integrate the knowledge of pre-trained BERT and vanilla NMT, namely asymptotic distillation, dynamic switch for knowledge fusion, and rate-scheduled updating. Besides, [45] used an APT framework for acquiring knowledge from pre-trained model to NMT, which included two modules: a) a dynamic fusion mechanism; b) a knowledge distillation paradigm.

Our approaches follow the previous BERT attention mechanism in BERT-fused NMT and introduce the switch gate mechanism into the model like CTNMT. Simultaneously, we also propose two other patterns to improve the model.

III. APPROACH

In this section, we first introduce the background of NMT, then present our methods in detail.

A. Background

NMT aims to maximize the conditional probability $p(y_1,\cdots,y_{T'}|x_1,\cdots,x_T)$, given a source and target sentence pair (\mathbf{x},\mathbf{y}) , where $\mathbf{x}=(x_1,x_2,\cdots,x_T)$ and $\mathbf{y}=(y_1,y_2,\cdots,y_{T'})$, T and T' are the length of \mathbf{x} and \mathbf{y} , respectively.

At training time, based on encoder-decoder architecture, NMT first transforms the input sentence with tokens x_1, x_2, \cdots, x_T into a sequence of hidden states $\boldsymbol{H} = \{\boldsymbol{h}_t\}_{t=1}^T$, and then uses the hidden states to predict the conditional distribution of each target token $p(y_j|\boldsymbol{H},y_{< j})$, given the previous ground truth target tokens [28]. The training loss on corpus \boldsymbol{C} is defined as:

$$L(\theta_{mt}) = \frac{1}{|C|} \sum_{(\mathbf{x}, \mathbf{y}) \in C} -\log P(\mathbf{y}|\mathbf{x}; \theta_{mt})$$
(1)

where θ_{mt} is a set of model parameters. At inference, the target sentence is generated by left-to-right decoding.

Different neural architectures have been proposed with the goal of improving effectiveness on NMT, in which Transformer [7] has shown strong results and surpassed prior state-of-the-art architectures based on recurrent networks [12], [29]. Thus, in this work, we choose Transformer as our base model.

Attention mechanism [11] is widely applied to the field of NMT, which focuses on important points and ignore other unimportant factors. The attention-based models allow a single token (e.g., a word or subword) in a sequence to be represented

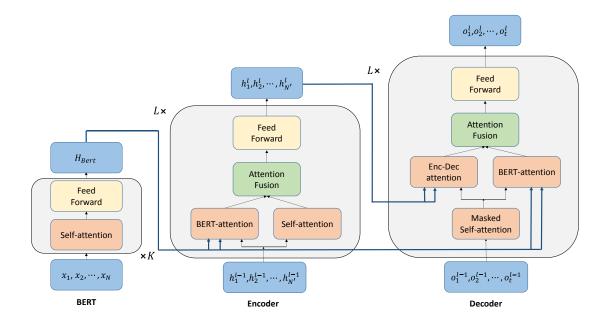


Fig. 1. The main architecture of our model

as a combination of all tokens in the sequence [29]. Let att(q,K,V) denote the attention model,in which q,K and V represent query, key and value respectively. q is a d-dimensional vector, and in this paper, K and V are the same matrices. Each $k_i \in K$ is also d-dimension vectors, $i \in [|K|]$. The attention model can be calculated by:

$$\alpha_i^T = \frac{1}{Z} \cdot \exp\left(\frac{\left(W_q q\right)^T \left(W_k k_i\right)}{\sqrt{d_k}}\right),\tag{2}$$

$$Z = \sum_{i=1}^{|K|} \exp\left(\frac{\left(W_q q\right)^T \left(W_k k_i\right)}{\sqrt{d_k}}\right) \tag{3}$$

$$\operatorname{att}(q, K, V) = \sum_{i=1}^{|V|} \alpha_i^T W_v v_i, \tag{4}$$

where W_q , W_K and W_V are parameters of the NMT model, and d_k is the dimension of each attention head.

B. Algorithm

In this section, we present three methods to incorporate BERT into NMT, and an illustration of our model is shown in Fig. 1. The whole training process can be summarized as follows step by step:

- Feeding the input x into BERT, Transformer encoder and decoder. Especially, we tokenize the input with BERT tokenizer and standard tokenizer respectively.
- Sending the output of BERT (usually the last layer) into the attention model named BERT-attention, then fuse the BERT-attention into self-attention or encoder-decoderattention [7] in each layer of encoder or decoder with three new methods.

• Training with the pre-trained Transformer model and frozen BERT model based on [7]. Continue the decoding process until meeting the end token.

The key difficulty of this training algorithm is to design the fusion methods of BERT-attention and self-attention or encoder-decoder attention. In this paper, we propose three different strategies: *linear aggregation*, *self-attention aggregation* and *switch-gate aggregation*.

1) Linear aggregation: Mikolov et al. [30] and Wu et al. [31] indicate the representation space of similar languages can be transmitted through the linear mapping. In our scenario, BERT-attention represents the universal information and Transformer represents the special downstream task information, which is in the same language. Intuitively, we can train a parameter matrix to balance the two parts.

Assuming x and y are the all source and target sentences from corpus C. For any sentence pair (x,y), where $x \in x$ and $y \in y$, let n_x and n_y denote the number of the units (e.g. wordpiece) in x and y. And we define H_{Bert} denoting the output of BERT. The $h_{Bert,i} \in H_{Bert}$ represents the i-th token of the input x through BERT encoding.

On Transformer encoder, let H_E^l be the hidden representation of the l-th layer. Specially, H_E^0 refers to the word embedding layer. Denote the i-th cell in H_E^l as e_i^l for any $i \in [n_x]$.

$$e_{i}^{l} = W_{i}^{l} \left(\operatorname{att}_{S} \left(e_{i}^{l-1}, H_{E}^{l-1}, H_{E}^{l-1} \right) + \operatorname{att}_{B} \left(e_{i}^{l-1}, H_{Bert}, H_{Bert} \right) \right), \forall i \in [n_{x}]$$
(5)

Where $W_i^l \in \mathbb{R}^{2d*d}$ (d means the dimension of word embedding) is the matrix to weigh the representation of BERT and vanilla NMT, and att_S and att_B represent attention models (4) with distinct parameters. Then each e_i^l is processed

by the non-linear activation unit, the norm layer [32] and the feed-forward neural network the same as standard Transformer [7]. The encoder eventually outputs H_E^L from the last layer.

During the Transformer decoder preceding time step t, let $O_{< t}^l = \left(o_1^l, \cdots, o_{t-1}^l\right)$ denotes the hidden state of l-th layer. Similar to vanilla NMT [7], o_1^0 is a special token that indicating the start of a sentence, and o_t^0 represents the embedding of predicted word at time-step t-1. In the l-th layer, o_t^l can be calculated as:

$$\tilde{o}_{t}^{l} = \operatorname{att}_{MS} \left(o_{t}^{l-1}, O_{< t+1}^{l-1}, O_{< t+1}^{l-1} \right)
o_{t}^{l} = \hat{W}_{i}^{l} \left(\operatorname{att}_{E} \left(\tilde{o}_{t}^{l}, H_{E}^{L}, H_{E}^{L} \right) \right)
+ \operatorname{att}_{B} \left(\tilde{o}_{t}^{l}, H_{BERT}, H_{BERT} \right)$$
(6)

Where att_{MS} , att_E and att_B are masked self-attention model, encoder-decoder attention model and BERT attention model respectively. After (6), o_t^l is handled by the non-linear activation unit, the norm layer and the feed-forward network, in which we can eventually obtain o_t^L . Then, put o_t^L into a linear transformation and softmax layer to get the t-th predicted word \hat{y}_t . When meeting $\langle EOS \rangle$ tag, the process of decoding finishes.

2) self-attention aggregation: In Transformer-based architectures, a self-attention mechanism is applied to draw global dependencies between inputs and outputs rather than the use of recurrence in neural networks [7]. We follow this idea and use it to find out which words the model should pay more attention to.

On Transformer encoder, different from the above method linear aggregation, self-attention aggregation mechanism first concatenates the self-attention calculated by the previously hidden representation and BERT-output attention unit as a new embedding D_E^l at l-th layer, then we send D_E^l to a new self-attention layer. Specially, we denote the i-th cell in D_E^l as d_i^l for any $i \in [n_x]$.

$$\tilde{d}_{i}^{l} = \left[a_{S} \left(d_{i}^{l-1}, D_{E}^{l-1}, D_{E}^{l-1} \right); a_{B} \left(d_{i}^{l-1}, H_{Bert}, H_{Bert} \right) \right]$$
(7)

$$d_i^l = \mathbf{a}_S \left(\tilde{d}_i^l, \tilde{D}_E^l, \tilde{D}_E^l \right) \tag{8}$$

Where \mathbf{a}_S and \mathbf{a}_B are shorthands of att_S and att_B respectively, [;] is the concatenation operation, which combines information from BERT and vanilla NMT model. Then each d_i^l is processed by a norm layer and a feed-forward network as a descending dimension layer. Finally, the encoder outputs D_E^L from the last layer.

On Transformer decoder, which is similar to the method on encoder side, we let $M_{\leq t}^l = \left(m_1^l, \cdots, m_{t-1}^l\right)$ represents the hidden state of l-th layer, during the Transformer decoder preceding time step t. In the l-th layer, m_t^l can be defined as:

$$\hat{m}_t^l = \mathbf{a}_{MS} \left(m_t^{l-1}, M_{< t+1}^{l-1}, M_{< t+1}^{l-1} \right) \tag{9}$$

$$\tilde{m}_{t}^{l} = \left[\mathbf{a}_{E} \left(\hat{m}_{t}^{l}, D_{E}^{L}, D_{E}^{L} \right); \mathbf{a}_{B} \left(\hat{m}_{t}^{l}, H_{Bert}, H_{Bert} \right) \right] \quad (10)$$

$$m_t^l = \mathbf{a}_{MS} \left(\tilde{m}_t^l, \tilde{M}_{< t+1}^l, \tilde{M}_{< t+1}^l \right)$$
 (11)

Then we add a linear descending dimension layer applying to m_t^l . The following steps are the same as the vanilla NMT model.

3) switch-gate aggregation: The gated recurrent cells have the ability to learn which data in a sequence should be kept in or left out [26], [33], inspired by which we propose to apply the similar idea of gates to the dynamic regulation of the balance of the information flowing from the pre-trained BERT or the vanilla NMT model. By doing that, they can pass relevant information down the long chain of sequences to make predictions [34].

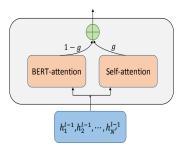


Fig. 2. The switch-gate aggregation

This mechanism has the same computation pattern on both Transformer encoder and decoder. Thus we adopt the encoder side as an example showed in Fig. 2. Formally, a context switch gate contains a sigmoid activation layer and an elementwise multiplication operation which can be defined as:

$$ATT_{S}^{l} = \|_{i=0}^{n_{x}-1} \operatorname{att}_{S} \left(e_{i}^{l-1}, H_{E}^{l-1}, H_{E}^{l-1} \right)$$
 (12)

$$ATT_{B}^{l} = \|_{i=0}^{n_{x}-1} \operatorname{att}_{B} \left(e_{i}^{l-1}, H_{Bert}, H_{Bert} \right)$$
 (13)

$$g_l = \sigma \left(W_l \cdot ATT_S^l + U_l \cdot ATT_B^l + b_l \right) \tag{14}$$

 ATT_S^l and ATT_B^l are concat layers that concatenate the self-attention and BERT output attention information respectively at l-th layer. Where $\sigma(\cdot)$ is the logistic function, H_E^l represents the hidden state of the vanilla NMT at l-th layer, H_{Bert} is the output of the pre-trained BERT model, and b_l is the bias. Then we integrate the NMT model and pre-trained BERT as:

$$H_E^l = g \odot ATT_S^l + (1 - g) \odot ATT_B^l \tag{15}$$

Where \odot refers to element-wise multiplication. If g is set to 0, which means completely ignoring the information on Transformer encoder, the network simply acts as the fine-tuning approach, and if g is set to 1, the network degrades to the vanilla NMT model. On the NMT decoder side, the calculation method is similar to the above.

TABLE I BLEU SCORES ON THREE IWSLT DATASETS

| System | Architecture | En-Fr | En-De | De-En | | |
|--------------------|----------------------------|---------|-------|-------|--|--|
| Baseline | | | | | | |
| Vaswani et al. [7] | Transformer base | 40.86 | 28.49 | 34.93 | | |
| Liu et al. [35] | Transformer base + RAdam | 41.01 | 28.52 | 34.98 | | |
| Lample et al. [5] | XLM + fine-tuning | 40.71 | 29.27 | 33.15 | | |
| Zhu et al. [15] | BERT-fused NMT | 41.59 | 30.28 | 35.90 | | |
| | Our NMT | systems | | | | |
| Ours | Self-attention aggregation | 42.03* | 30.37 | 35.29 | | |
| Ours | Linear aggregation | 41.80 | 30.29 | 35.41 | | |
| Ours | Switch-gate aggregation | 42.12 | 30.62 | 36.15 | | |

[&]quot;*" indicates that we only fuse the last layer of Transformer and BERT (See subsection "About NMT layers" for more details)

IV. EXPERIMENTS

We conduct our experiments on English \leftrightarrow German and English \rightarrow French tasks to verify our approach, the training details are as follows.

A. Datasets

For the rich-resource scenario, we work on WMT'14 En \rightarrow De task ¹, whose corpus size is 4.5M. newstest2013 is used as the validation set and newstest2014 as the test set, which is the same as [7].

For the low-resource scenario, the English \leftrightarrow German training set is from IWSLT'14 [36] that compromises 160k sentence pairs. We lowercase all words, split 7k sentence pairs from the training dataset for validation and concatenate dev2010, dev2011, tst2010, tst2011, tst2012 as the test set [37], [38]. For English \rightarrow French task, we choose IWSLT'17 as our training set, which contains 236k sentence pairs. we use dev2010 as our validation and the fusion of tst2010, tst2011, tst2012, tst2013, tst2014 and tst2015 as our test set.

In all translation tasks, we tokenize all data with MOSE tokenizer [39], and apply byte pair encoding (BPE) [40] to encode words through sub-word units. We build shared vocabularies of 32K, 10K and 16k sub-words for WMT'14 English \rightarrow German, IWSLT'17 English \rightarrow French respectively. We measure the translation quality with BLEU scores [41].

B. Training Details

To make this work easier to reproduce, this paper gives detailed strategies for training the proposed model. All experiments run on *fairseq-py*² [42].

For WMT'14 En \rightarrow De task, the model configuration is $transformer_wmt_en_de$, in which the embedding size is 512, attention heads are 8 and feed-forward layer dimension is 2048. The hyper-parameters setting resembles [7].

For other low-resource tasks, the model configuration is $transformer_iwslt_de_en$, representing a six-layer model with embedding size 512 and feed-forward neural network dimension 1024. We employ adam [43] as the optimization of the network with $\beta_1 = 0.9$, $\beta_2 = 0.98$ and weight - decay

= 0.0001. The learning - rate is 0.0005 with inverse_sqrt scheduler, where warmup-init-lr is 10^{-7} . Label smoothing $\varepsilon_{ls} = 0.1$ is used as regularization [44]. We set the batch size to 4000 per batch and limit sentence length to 100 BPE tokens. Note that the above hyperparameter settings are the same as those used in the baseline models.

We choose BERT-base-uncased³ model for English \rightarrow German and English \rightarrow French tasks and Bert-base-german-cased⁴ model for German \rightarrow English. The BERT model is frozen during training. Besides, on the *self-attention aggregation* mechanism, we set attention fusion heads to 4 and 8 for IWSLT and WMT tasks respectively.

We first train an NMT model until convergence and initialize our model with the obtained model, and the rest parameters are initialized with xavier uniform. For English → German task, we choose the second-to-last hidden states of BERT to help the training of the vanilla NMT model, while the last layer of BERT is adopted in other tasks.

C. Main Results on IWSLT Datasets

The BLEU scores of IWSLT translation tasks are reported in TABLE I. We compare our system with the other four systems including a) Transformer base [7], b) RAadm which is a theoretically sound variant of Adam [35], c) XLM which is a crosslingual pre-trained language model, and d) BERT-fused NMT [15], in which BERT-fused NMT is the strongest baseline that has significant advantages over other three baselines. On the above tasks, we reproduce the experiments presented in the four baseline paper. However, We do not achieve the results in [15].

In our model, we evaluate the effectiveness of the proposed three strategies respectively. Obviously, switch-gate performs best over the other two patterns, and improves the BLEU scores of the three tasks by 1.26, 2.13, 1.22 points respectively, demonstrating the effectiveness of our method. Linear aggregation algorithm also has a great improvement on En \rightarrow Fr translation task by 0.94 BLEU. However, the self-attention mechanism does not achieve our expected results on IWSLT'14 De \rightarrow En task, and even performs further worse

¹http://www.statmt.org/wmt14/translation-task.html

²https://github.com/pytorch/fairseq

³https://s3.amazonaws.com/models.huggingface.co/bert/bert-base-uncased-pytorch_model.bin

⁴https://s3.amazonaws.com/models.huggingface.co/bert/bert-base-german-cased-pytorch_model.bin

TABLE II BLEU scores on WMT' 14 EN \rightarrow DE dataset

| System | Architecture | BLEU | | |
|--------------------|------------------------------|--------|--|--|
| Baseline | | | | |
| Vaswani et al. [7] | Transformer base | 27.31 | | |
| Yang et al. [17] | + Dynamic switch | 29.40* | | |
| Weng et al. [45] | + Dynamic fusion | 28.77 | | |
| Weng et al. [45] | + knowledge distillation | 29.23 | | |
| Vaswani et al. [7] | Transformer big | 28.46 | | |
| Lample et al. [5] | + Fine-tuning | 27.70 | | |
| Lample et al. [5] | + Frozen feature | 28.70 | | |
| Our NMT systems | | | | |
| Ours | Transformer base | 27.37 | | |
| Ours | + Self-attention aggregation | 28.87 | | |
| Ours | + Linear aggregation | 29.11 | | |
| Ours | + Switch-gate aggregation | 29.51 | | |

[&]quot;*": beam size is 8 and the dimensions of hidden states are 768

than BERT-fused NMT. We analyze the following two reasons for this result. Firstly, we consider that some information is lost when BERT attention unit and vanilla NMT self-attention unit are merged. In the future work, we will verify this assumption. Secondly, the self-attention module is updated through the backpropagation of the loss between the label and the predicted value. No other supervision information is introduced. Therefore, the supervision of the model is limited and it is easy to overfit the label.

D. Main Results on WMT'14 En \rightarrow De Dataset

The results on WMT'14 En \rightarrow De dataset are presented in TABLE II. We compare our model with several strong baselines including Transformer and some pre-trained methods in NMT.

Compared with Yang et al (CTNMT) [17], we also apply the gate mechanism to the decoder side. Experiments show that although their dimensions of all the hidden states and beam size values are larger, our *switch-gate aggregation* method still performs better. Weng et al. [45] propose an APT framework to acquire knowledge from the pre-trained model to NMT, which also has a dynamic fusion mechanism to fuse task-specific features adapted from general knowledge into NMT network. The biggest difference between our fusion methods is the different granularity, in which Weng et al. calculate each token of each layer in the Transformer and the pre-trained model. However, it is not that the finer the calculation granularity, the better the translation effect. According to experiments, except for the *linear aggregation* method, our BLEU scores are higher than them.

Transformer big model with fine-tuning even falls behind the baseline, and with a frozen feature approach during fine-tuning, it achieves a few gains over the Transfomer big model. The experimental results are consistent with our intuition that fine-tuning will cause *catastrophic forgetting problem* [18] and also verify the fine-tuning method does not fit NMT. All our methods with Transformer base architecture are better than the Transformer big model whose parameter size is far larger than ours.

TABLE III
RESULTS OF ABLATION STUDY (%).

| Settings | BLEU |
|---|-------|
| Transformer base | 40.86 |
| Switch-gate aggregation | 42.12 |
| BERT-encoder attention | 41.57 |
| feed BERT to all layers | 41.45 |
| BERT-decoder attention | 41.95 |
| feed BERT to all layers | 41.82 |
| - without frozen BERT | 41.53 |
| aggregation-dropout | 41.93 |
| - pre-trained NMT model | 41.07 |
| Linear aggregation | 41.80 |
| BERT-encoder attention | 41.27 |
| BERT-decoder attention | 41.64 |
| - without frozen BERT | 41.42 |
| aggregation-dropout | 41.47 |
| - activation-function | 41.59 |
| Self-attention aggregation | 42.03 |
| - BERT-encoder attention | 41.44 |
| - BERT-decoder attention | 41.63 |
| - aggregation-dropout | 41.86 |

E. Ablation study

We conduct the following studies and the corresponding results can be found in TABLE III. The experiments are mainly conducted on IWSLT'14 En \rightarrow Fr translation task.

1) For switch-gate strategy: We first verify whether each component is essential: we remove the BERT-encoder attention in (12-15) (i.e., att_B). The BLEU score drops from 42.12 to 41.57, which shows attention models are important for better performance. Besides, we feed BERT into the last layer of the decoder instead of all layers, and it makes BLEU scores drop by 0.12 points. It suggests that incorporating BERT into all layers can more fully fuse the two parts of information. The operation of removing BERT-decoder attention is similar to the above, which leads to a notable decrease in BLEU. Obviously, adding BERT into the encoder is more effective than the decoder. Then we jointly train the vanilla NMT model with BERT model. Although it can also boost the baseline from 40.86 to 41.53, it is not as good as freezing the BERT model. Aggregation-dropout is removed afterward, which is a dropout net after (15), and BLEU score drops by 0.19 points slightly. Finally, we train the NMT model from a randomly initialized model instead of using a pre-trained fairseq Transformer model, BLEU score affects a significant decline by 1.05 points comparing to 42.12, which nearly catches up the baseline.

2) For the other two strategies: We conduct similar experiments on linear aggregation and self-attention aggregation. We also find BERT attention models are important for better performance, in which BERT-encoder attention is more effective. Especially on the linear aggregation strategy where we remove the non-linear activation unit, which is the next step of (5) and (6). The BLEU score is 41.59, not as good as our proposed method. On the self-attention aggregation strategy, we just apply BERT to the last layer of the vanilla NMT, and there is a significant decline in the results of removing different

TABLE IV
RESULTS ON IWSLT WITH DIFFERENT LAYERS OF VANILLA NMT

| Model | Layers | BLEU |
|----------------------------|----------------|-------|
| Transformer | N/A | 40.86 |
| Embedding | N/A | 41.38 |
| | 1st \sim 5th | 41.54 |
| Switch-gate aggregation | Last layer | 41.93 |
| | All layers | 42.12 |
| | 1st \sim 5th | 41.59 |
| Linear aggregation | Last layer | 41.71 |
| | All layers | 41.80 |
| | 1st \sim 5th | 41.55 |
| Self-attention aggregation | Last layer | 42.03 |
| | All layers | 41.64 |

modules, which is similar to linear aggregation strategy.

The above experiments and analysis can demonstrate how our approaches work and point out the effectiveness of each component in our architecture.

F. About NMT layers

We compare the effectiveness of applying our methods to different layers of vanilla NMT model on IWSLT'17 En \rightarrow Fr dataset. The results are shown in TABLE IV. *Embedding method* means using pre-trained BERT as inputs to the NMT model, leaving the underlying linguistic information ignored, inspired by [1]. $1st \sim 5th$ represents integrating BERT into the first 5 layers of the Transformer model, while *Last layer* only fuses BERT with the last layer of the Transformer, and *All layers* are incorporating BERT into all levels of Transformer.

On the embedding layer, the pre-trained embedding performs better than the embedding from the vanilla NMT, which can get a considerable improvement. Moreover, all of our methods are better than using pre-trained models as inputs to the NMT model.

On the Switch-gate aggregation and Linear aggregation mechanism, All layers obtain the best performance, while Last layer performs best on Self-attention aggregation. We think that the first two methods Switch-gate aggregation and Linear aggregation are essentially weighted fusion of the BERT and transformer representations, and adding more layers is equivalent to adding more additional information to each layer of the NMT model according to its requirements, thus the experimental result of All layers displays best. In contrast, Selfattention aggregation is merging the BERT and transformer representations into a new vector, and then automatically learn the information required for the machine translation task. We think that the shallow layers of Transformer focus on transforming the input representation to the high layer, and not directly connected to downstream tasks, so the external contextual knowledge does not help them much. Besides, High layers of the Transformer can obtain more gain from BERT compared with low layers.

G. About BERT layers

BERT captures the structure properties of language and composes a hierarchy of linguistic signals ranging from surface to semantic features [23].

TABLE V RESULTS ON IWSLT WITH DIFFERENT LAYERS OF BERT

| Model | $En \rightarrow De$ | $\mathbf{En} 	o \mathbf{Fr}$ |
|-----------------------------|---------------------|------------------------------|
| Last Hidden Layer | 30.51 | 42.12 |
| Second-to-Last Hidden Layer | 30.62 | 41.64 |
| Third-to-Last Hidden Layer | 30.41 | 41.32 |
| Fourth-to-Last Hidden Layer | 30.40 | 41.28 |

In [17], they find that the second-to-last layer of BERT works significantly better than the last hidden state. However, they only experimented on WMT14 English \rightarrow German corpus, which represents the rich-resource scenario containing 4.5M parallel data.

We experiment on a low-resource scenario with *switch-gate aggregation* algorithm, in which we choose IWSLT'14 English \rightarrow German, and IWSLT'17 English \rightarrow French datasets. The results are shown in TABLE V.

On IWSLT'14 En \rightarrow De translation task, we find that the second-to-last layer of BERT works best comparing with other hidden states, while on IWSLT'17 En \rightarrow Fr translation task, the last layer performs significantly better than the second-to-last layer. Intuitively, the last layer of BERT focuses more on downstream tasks and better represents information at the semantic level. So on English \rightarrow German, the last layer is biased to the LM tasks. However, on English \rightarrow French translation task, where some words in English and French are close or even the same, the last layer of the BERT model works best with relatively similar semantic space.

V. CONCLUSION AND FUTURE WORK

In this work, we propose three simple but effective approaches for neural machine translation to incorporate BERT into Transformer, i.e., self-attention aggregation, linear aggregation and switch-gate aggregation, in which the BERT model is fully utilized by the encoder and decoder. Among the above methods, switch-gate aggregation performs best on several translation tasks, which leverages the gate mechanism to dynamically control the balance of the information flowing from the pre-trained BERT or the Transformer model. While the empirical results are strong, switch-gate aggregation surpasses Transformer-base by 2.13 BLEU score on IWSLT 14 English → German translation task. On other tasks, our approaches also achieve remarkable performance.

For future work, we consider starting from the semantic level to more refinedly extract the information related to the machine translation task in the BERT model. Then we want to compress the model and speed up inference time.

VI. ACKNOWLEDGMENT

This work is supported by the National Natural Science Foundation of China (No.61732005, No.61671064) and the National Key RD Program of China under Grant (No.2018YFC0832104).

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