COMPARISON OF DIFFERENT INFORMATION FLOW ARCHITECTURES IN AUTOMATED DATA COLLECTION SYSTEMS

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Abstract: Automated Data Collecting System (ADCS) is a common name for automatic systems that collect data of any kind. These systems are becoming more and more common in several industries and play an important part in many of today's and future applications. Information flow architecture is an important issue, when employing an ADCS. This paper presents different kinds of architecture models and their typical characteristics, concentrating on traffic load issues in different parts of the system. The results presented in this paper, give a basis for more accurate specifying and designing of the architecture model for each automated data collecting application in question.

1 INTRODUCTION

Information flow architectures play an important role in many present day and especially future applications. As automatization becomes more common in many industries, the problem of information flow architecture must be solved. This actually consists of several "sub-problems": where data is transferred, how it is transferred, where data is stored, who can access the data, how the access is performed, what configuration is needed and which party performs them, how the new participant is added etc. etc. (Jie et. al., 2006)

All the above questions must be answered to make the system optimally suited for an intended application. Every application has its own individual characteristics and therefore a common answer for the information flow architecture cannot be given. All the options have their own pros and cons, and these are discussed in this study. The main focus is however in comparing throughputs and traffic loads in different parts of the Automated Data Collecting Systems (ADCS) and in different models.

ADCS is defined here as including all types of automatic systems that collect any kind of data. Well known examples can be, for example, RFID-systems, supply chain management systems, automatic meter reading (AMR) systems, forest fire surveillance sensor networks or highway speed control systems. The common factor is that systems collect data and in some way make it available for their users. (Bodrozic, Stipanicev, Stula, 2006; Wang et. al., 2005)

An ADCS usually consists of data collection units (DCU) (e.g. RFID readers or water consumption meters), database(s), optional server(s) and network and data links between these components. All of the components have an effect on the nature and behaviour of the system. Therefore, the components must be chosen based on the needs of the application in question. Video data stream systems transfer large amounts of data and they require small jitter and high throughput due to their real time operation. AMR systems transfer small amounts of data and also the real time demand is very low. Supply chain management systems also deal with small data quantities, but they might need very short response times and delays, for example where handling machines are exploiting the data. EDI systems (Electronic Data Interchange) do not usually demand real time features, but the transferred data amount might still be high. Forest fire surveillance sensor networks put a lot of emphasis on energy efficiency, because of the need for long maintenance intervals (Yu, Wang, Meng, 2005)

Depending on which application the ADCS is designed to be used in, different attributes must be

emphasized. For AMR systems it is not recommended or necessary to roll out a system with effective and high-cost real time operations. In supply chain management it can be considered needless expense to employ a system with very high throughput, instead of concentrating resources on keeping delays low.

The simulations presented in this study present the differences in traffic load in different architectures. These results give a basis for specifying and designing a suitable system for each application. This paper is sectioned as follows: chapter 2 presents three different architecture models and their main characteristics. Chapter 3 contains the simulation descriptions and TCP theory, and traffic load simulation results and discussion are presented in chapter 4. Finally, chapter 5 concludes the study and also takes a look at future work.

2 ARCHITECTURE MODELS

The simulations were done with three different types of architecture model. These were *centralized, semidistributed* and *distributed* architectures. The differences between these architectures are:

• The placement and number of data storage(s) e.g. database(s)

- One-way or two-way traffic
- Reaching the database directly or through a dedicated server

All links in the simulation models are marked as A, B, C or D, depending on their characteristics. A, B and C links have 100 Mbps capacity whereas D has 10 Mbps. The delay for every link is 1 μ s and BER is 0 %. The same delay and BER are also used for every node in the network as is the buffer size of 50 packets.

2.1 Centralized Architecture Model

The centralized architecture model consists of one server, 12 data collection units (DCUs), 6 switches and 7 routers (GWs) as seen in figure 2.1.

In this simplified model of centralized architecture, all data is stored in the one dedicated server and all users can access the data through that server. This means that the information flow is considered as uni-directional. The links themselves are however bi-directional, as TCP/IP-connections always are, because of the protocol requirements, acknowledge-packets etc.

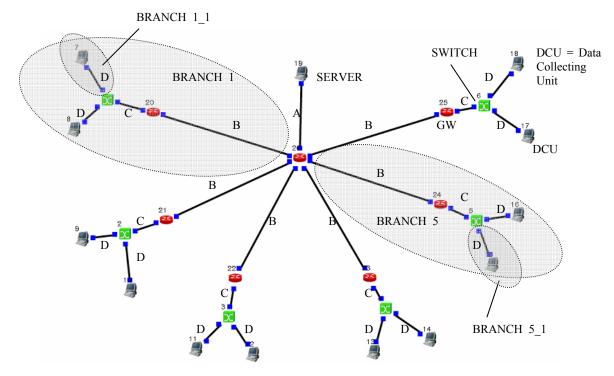


Figure 2.1: Centralized architecture model. Data is stored in the server.

In this model the DCUs send their data direct to server. Other components like switches or GWs only forward the data packets to the following link.

2.2 Semi-Distributed Architecture Model

The semi-distributed architecture model consists of the same components as the centralized model and the used topology is also similar as presented in figure 2.1. In this model the data is however stored in several databases, which are located in every GW. However users will always access the data through a dedicated server, which requests the data in question from each database as needed. Due to these GWdatabases, only the on-demand data is transferred beyond its own GW, which decreases the traffic load in the server and A/B links significantly.

In this procedure, the information flow is unidirectional between DCUs and GWs and bidirectional between GWs and the server due to the queries the server uses to request data from GWs.

2.3 Distributed Architecture Model

Unlike the two other architecture models presented above, the distributed architecture model does not have a server. Other components remain the same as in figure 2.2. In this model users access data, or actually the GW which hosts the database, directly from their own branches (or subnets), not through any dedicated server as in the previous architecture models. The user requests the needed information from a specific GW by sending a query packet(s). The GW then sends the data back to the user.

3 SIMULATIONS

These simulations were performed with the NCTUns Network simulator 3.0 by SimReal Inc, which uses a novel kernel re-entering simulation methodology (Wang et al 2003). The purpose of the simulations was to find the changes in link loads between different architectures.

3.1 Generated Traffic

The generated traffic sequence was similar in all three architectures. The modelled time period was 40 seconds and each DCU produced data for one continuous 10 second period. In the centralized architecture model data was transmitted directly from DCUs to the server, whereas in the semidistributed and distributed models the data was first stored into GWs, and then requested from there by the server or other DCU.

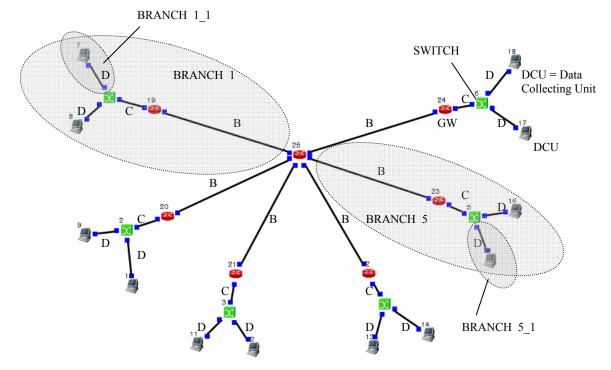


Figure 2.2: Distributed architecture model. Data is stored in the GWs.

These queries lasted 1 second each, as did the answers (e.g. data transfers) for them. Each GW received two of these queries. This means that 10 % of the data each DCU produced was requested by the users and transferred from the databases.

This simulated traffic used basic TCP protocol with 1024 B of payload and all connections used their own individual TCP port numbers (*Transmission Control Protocol*, 1981). Two major characteristics of TCP are powerful mechanisms for error correction and congestion avoidance, which make it suitable for this kind of use, where data is error critical and congestions are highly likely to exist at some point.

The congestion control mechanism of TCP protocol consists of two procedures: *slow start* and *congestion avoidance*. In slow start the extra window for sender, *the congestion window* (*cwnd*), will be taken into use. The congestion window defines the number of sent segments before an acknowledgement packet is expected to arrive. At the beginning of transmission, the cwnd is 1. When acknowledgement for this first sent packet arrives, the value of cwnd is doubled. This is done after every successful transmission. (Allman et al, 1999)

When the first error occurs, the sender switches to the congestion avoidance procedure to reduce growth speed and achieve network capacity less aggressively. This switching point is called *slow start threshold, sstresh*. The increase in the size of the congestion window, and the number of sent segments before acknowledgements, will continue. The value is increased by one per every *round trip time*. The *round trip time* is a calculated time for a packet to travel from sender to receiver and the receiver's acknowledgement to travel back to the original sender. The increase is now linear, whereas in the slow start phase it was exponential. Eventually, the packet will be lost again. Now the *cwnd* is reset back to 1, and *sstresh* is set to the value of half the current window size. Now the transmission continues with the slow start procedure again, until an error occurs, or the *cwnd* reaches the *sstresh* value, and switches again to congestion avoidance procedure. (Allman et al, 1999)

The transmission continues performing these mechanisms, all the time seeking the current maximum network capacity. It is important to realize, that the *sstresh* does not always fall, it can also rise. If the error in congestion avoidance occurs when the window size is more than twice the *sstresh*, the *sstresh* will increase. The following figure 3.1 presents the changes in the *cwnd* and *sstresh* during slow start and congestion avoidance procedures. Other TCP congestion avoidance algorithms have also been developed, but they are not discussed here, since the focus of this study is in architecture models, not in protocols (Wikipedia, 2007).

TCP protocol was selected for these simulations because it is very commonly used in several kinds of applications and is designed to act well in difficult circumstances. Another protocol option considered was User Datagram Protocol (UDP), which is "lighter" and a connectionless protocol. UDP does not have error correction or congestion avoidance procedures, but because of its low overhead features, it would suit low-power consumption systems well. However systems demanding very low power consumption usually have their own application specific and customized protocols, such as the Kilavi protocol used in building automation (Soini et. al., 2006).

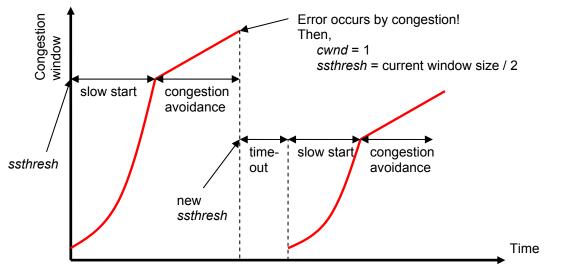


Figure 3.1: The use of congestion window and slow start threshold in TCP transmission (Allman et al, 1999).

4 RESULTS AND DISCUSSION

Throughputs in A- and B-links can be seen from the following graphs. The figure 4.1 shows server link A traffic load in centralized and semi-distributed architectures.

As can be seen, the throughput is substantially lower in the semi-distributed architecture than in the centralized model. This also leads to much lower load on and requirements for the dedicated server. The traffic in link B is shown in figure 4.2. The picture presents the corresponding graphs from three different architectures. The presented load is measured from branch 5 (as in the graphs in figures 4.3 and 4.4).

As can now be seen, the traffic load in the centralized model is much higher and more continuous than in the other two models. The distributed model has more "spikes" than the semidistributed, due to data queries, which come directly from DCUs and not from the dedicated server. These queries also produce traffic for link B.

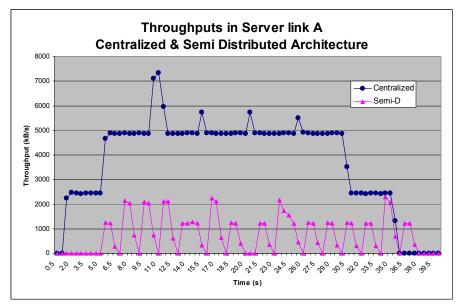


Figure 4.1: Link A throughputs in centralized and semi-distributed architecture models.

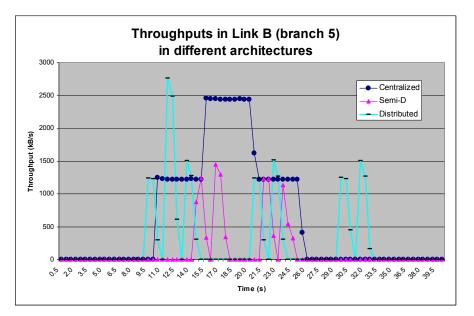


Figure 4.2: Link B throughputs in all three architecture models.

Examining link C it can be seen that data collecting traffic from DCUs is similar in all architecture models. This is presented in figure 4.3.

Graphs indicate that the only difference appears in the distributed model, where data queries also produce load in the link. These queries can be seen as an extra "double spike". In all the other situations it does not matter which architecture model is used when considering traffic load in link C.

These characteristics can also be seen when examining the traffic load of link D, as can be seen in figure 4.4.

When examining the centralized architecture model, a few typical characteristics can be discovered. First of all the traffic load in all links is very high and also continuous. Huge differences compared to the other architectures emerged in links A and B. This leads to the conclusion that server and link capacity must be high for centralized architecture to work well, or alternatively, the amount of collected data must be small. This, added to the fact that administering this kind of one database system is much easier and simpler than systems with several databases due to user

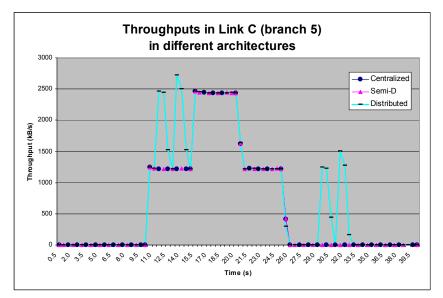


Figure 4.3: Link C throughputs in all three architecture models.

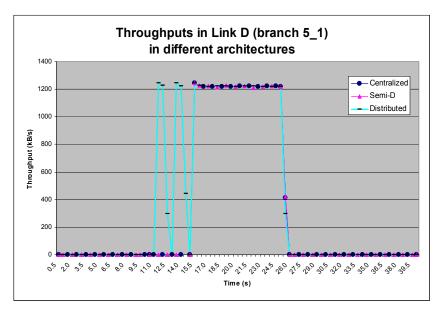


Figure 4.4: Link D throughputs in all three architecture models.

authentication configurations, means that centralized architecture is suitable for ADCS if the system is small and the amount of collected data is also relatively small. Also adding a new DCU is quick and easy because it only communicates with one partner, the server.

The semi-distributed architecture model produced significantly less traffic than the centralized model with the systems main links A and B. This is because only required information is transferred beyond the databases (or gateways in this case). A semi-distributed model is however more complicated to administer, because of distributed resources and databases throughout the system. On the other hand these divided resources do reduce the requirements placed on the equipment, which makes the whole ADCS more reliable and cost-effective. Adding a new DCU or configuring user authentication rules for semi-distributed systems is easy, because all the information is distributed through one dedicated server, which is the only communication partner for the databases. The semidistributed architecture model is therefore suitable for automated data collecting systems, which have rather large numbers of DCUs and architecture or topology which might change regularly.

The distributed architecture model differs from the other two, because it does not have a server or server link A. The traffic load in link B is quite similar to that of the semi-distributed model, but the distributed model has data queries coming from DCUs too. This slightly increases the throughput, but still the traffic load is much lower than in the centralized model. The distributed model is hard to administer, because of the several databases and communication partners all over the system. Adding a DCU is also complicated, because it needs to communicate and authenticate with several partners. The distributed architecture model is most suitable for an ADCS with a large amount of data and many DCUs, but the architecture is likely to be fixed and new users or DCUs are not expected to be added frequently.

The traffic load in links C or D is very similar in all simulated architectures. Only the distributed model has slightly more traffic here, because data queries come straight from DCUs. Still, the difference is marginal, when most of the traffic load is generated from collected data which is similar in all models.

The security aspects constitute an entity which, despite being essential for each application, is not discussed extensively in this paper. The main security issues for information flow architectures are user authentication and data encryption, which differ more or less for each model. The common factor is that they usually increase system complexity and also traffic load in each model. The need and level of encryption is strongly dependent on the nature of application in use. User authentication, on the other hand, is substantially different for each architecture models, due to different numbers of communication partners, as mentioned earlier. These aspects however require more specific investigation to accurately determine requirements and possibilities for different user authentication methods. (Sikkilä et. al., 2006; Perrig et. al., 2002)

The main characteristics of all three studied models are summarized in the following table 4.1.

5 CONCLUSIONS AND FUTURE WORK

This paper presented three different information flow architecture models for automated data collecting systems, and the main characteristics of each of them. Comparisons of the traffic loads in each part of the systems were also presented, and suitable models for different application types were recommended. These presented results can be used as a basis for designing and specifying an application-specific automated data collecting system.

| Model | Traffic load | Maintenance | Modifiability | Number of DCUs | Example applications |
|----------------------|--------------|-------------|---------------|-------------------|-------------------------|
| Centralized | High | Very easy | Very good | Small | Video surveillance |
| Semi- Distributed | Low | Easy | Good | Large | Water meter reading |
| Distributed | Low | Hard | Bad | Very large | Supply chain management |

Table 4.1: The main characteristics of different information flow architecture models for ADCS.

As mentioned earlier, every application has its own characteristics and requirements for ADCS. Therefore more application specific studies must be made with each area of intended use in mind. In supply chain management the supply chain must be accurately studied, because even supply chains for different products may have very different needs. In AMR systems the metering environment and needs must be strictly surveyed to achieve an optimal outcome. Therefore this study will be continued with a more accurate definition of the supply chain in the paper reel industry and implementation of an RFIDbased ADCS in the paper industry environment. Also the security issues such as user authentication methods will be studied more deeply to determine the procedure options and requirements for adding new parts and partners to ADCS.

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